## Non-Destructive Evaluation (NDE)

### Chapter 6

## **Ultrasonic Testing**



#### Mohamad Fathi GHANAMEH



## **Ultrasonic Testing (UT)**

- > Sub-surface detection
- ➤ This detection method uses high frequency sound waves, typically above 2MHz to pass through a material
- ➤ A probe is used which contains a piezo electric crystal to transmit and receive ultrasonic pulses and display the signals on a cathode ray tube or digital display
- > The actual display relates to the time taken for the ultrasonic pulses to travel the distance to the interface and back
- > An interface could be the back of a plate material or a defect
- > For ultrasound to enter a material a couplant must be introduced between the probe and specimen





## Advantage of Ultrasonic Testing

- > Sensitive to both surface, subsurface and internal discontinuities or even planar discontinuities.
- > Depth of penetration for flaw detection or measurement is superior to other methods.
- > Only single-sided access is needed when pulse-echo technique is used.
- ➤ High accuracy in determining reflector position and estimating size and shape.
- Minimal part preparation required.





## **Advantage of Ultrasonic Testing**

- > Electronic equipment provides instantaneous results (Rapid results).
- Detailed images can be produced with automated systems.
- ➤ Has other uses such as thickness measurements, in addition to flaw detection.
- > Safe
- > May be battery powered and so it's Portable





## **Limitations of Ultrasonic Testing**

- > Surface must be accessible to transmit ultrasound.
- > Skill and training is more extensive than with some other methods.
- ➤ Normally requires a coupling medium to promote transfer of sound energy into test specimen.
- ➤ Materials that are rough, irregular in shape, very small, exceptionally thin or not homogeneous are difficult to inspect.
- > Cast iron and other coarse grained materials are difficult to inspect due to low sound transmission and high signal noise.





## **Limitations of Ultrasonic Testing**

- Linear defects oriented parallel to the sound beam may go undetected.
- > Difficulty on detecting volumetric defect
- > Reference standards are required for both equipment calibration, and characterization of flaws.
- No permanent record





### **Principles of Ultrasonic Inspection**

- ➤ Ultrasonic waves are introduced into a material where they travel in a straight line and at a constant speed until they encounter a surface.
- > At surface interfaces some of the wave energy is reflected and some is transmitted.
- ➤ The amount of reflected or transmitted energy can be detected and provides information about the size of the reflector.
- > The travel time of the sound can be measured and this provides information on the distance that the sound has traveled.





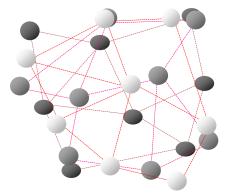
- > Ultrasonic waves are very similar to light waves in that they can be reflected, refracted, and focused.
- > Reflection and refraction occurs when sound waves interact with interfaces of differing acoustic properties.
- ➤ In solid materials, the vibrational energy can be split into different wave modes when the wave encounters an interface at an angle other than 90 degrees.
- ➤ Ultrasonic reflections from the presence of discontinuities or geometric features enables detection and location.
- > The velocity of sound in a given material is constant and can only be altered by a change in the mode of energy.





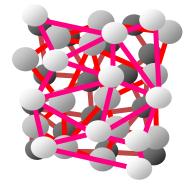
- > Sound is produced by a vibrating body and travels in the form of a wave.
- > Sound waves travel through materials by vibrating the particles that make up the material.

gas



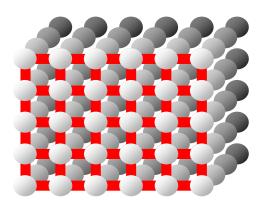
- low density
- weak bonding forces

liquid



- medium density
- medium bonding forces

solid

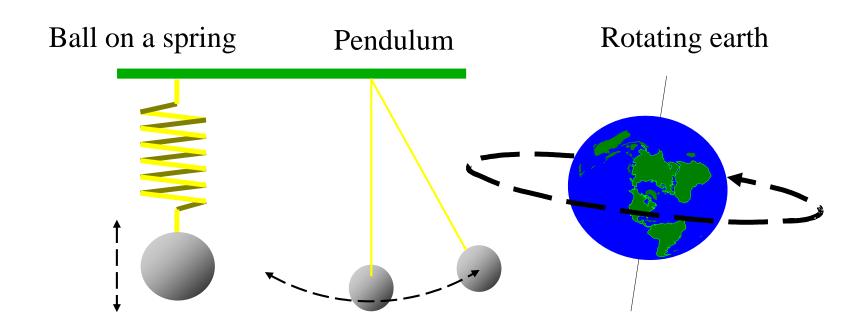


- high density
- strong bonding forces
- crystallographic structure



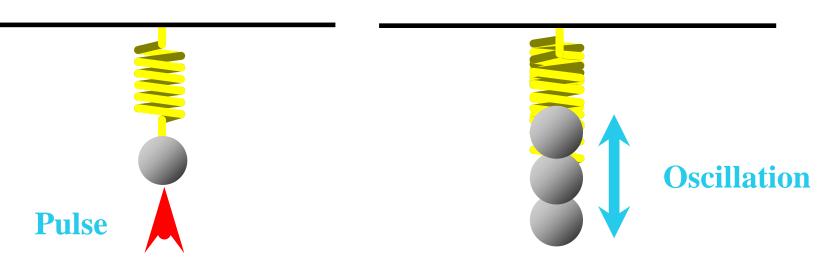


#### > Examples of oscillation



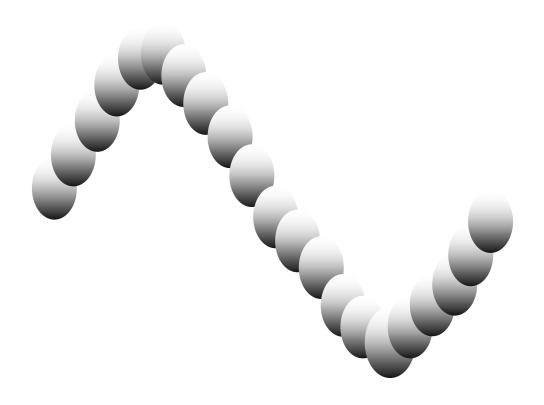


#### > Oscillation

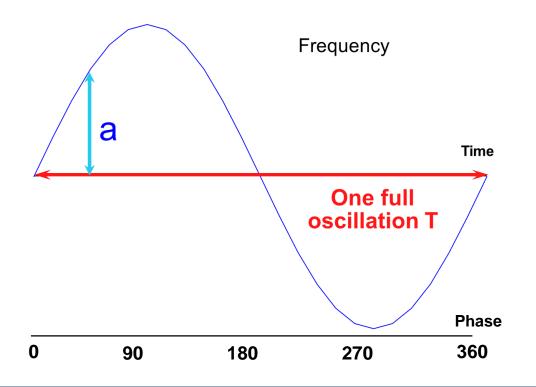


The ball starts to oscillate as soon as it is pushed

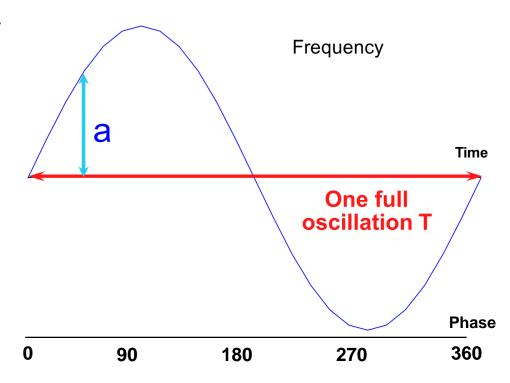
> Movement of the ball over time

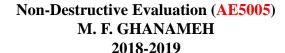


> The pitch of the sound is determined by the frequency of the wave (vibrations or cycles completed in a certain period of time).



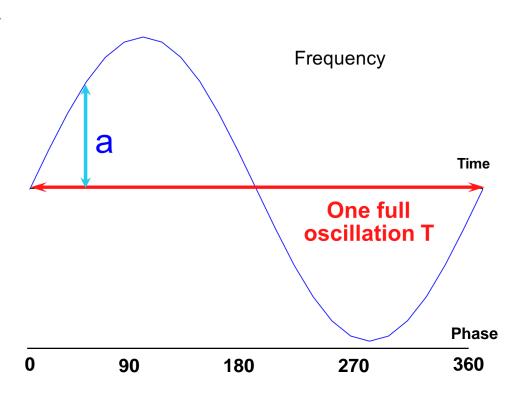
- From the duration of one oscillation T the frequency f (number of oscillations per second) is calculated  $f = \frac{1}{T}$
- The actual displacement **a** is termed as  $a = A\sin\phi$
- The measurement of sound waves from crest to crest determines its wavelength  $(\lambda)$ .





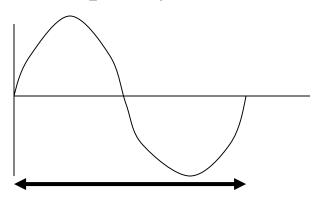


- The time is takes a sound wave to travel a distance of one complete wavelength is the same amount of time it takes the source to execute one complete vibration.
- The sound wavelength is inversely proportional to its frequency. ( $\lambda = 1/f$ )

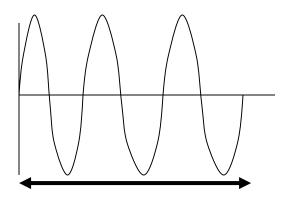




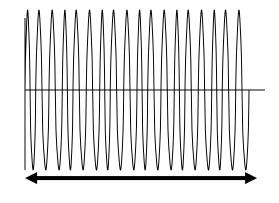
Frequency: Number of cycles per second



1 second 1 cycle per 1 second = 1Hertz



1 second 3 cycle per 1 second = 3Hertz



1 second 18 cycle per 1 second = 18 Hertz

The Higher The Frequency The Smaller The Wavelength

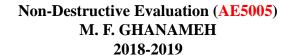
- 1 Hz = 1 cycle per second
- 1 Kilohertz = 1 KHz = 1000Hz
- 1 Megahertz = 1 MHz = 1000 000Hz
- The higher the frequency the smaller the wavelength
- The smaller the wavelength the higher the sensitivity
- Sensitivity: The smallest detectable flaw by the system or technique
- In UT the smallest detectable flaw is  $\frac{1}{2}\lambda$  (half the wavelength)





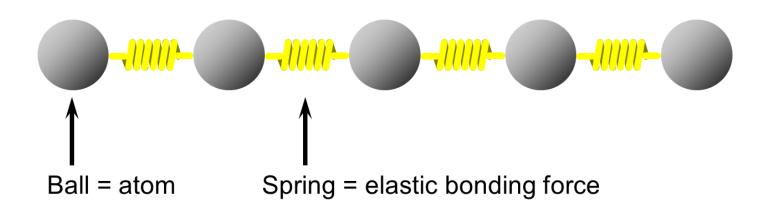
#### > Spectrum of sound

Frequency range Hz	Description	Example
0 - 20	Infrasound	Earth quake
20 - 20.000	Audible sound	Speech, music
> 20.000	Ultrasound	Quartz crystal

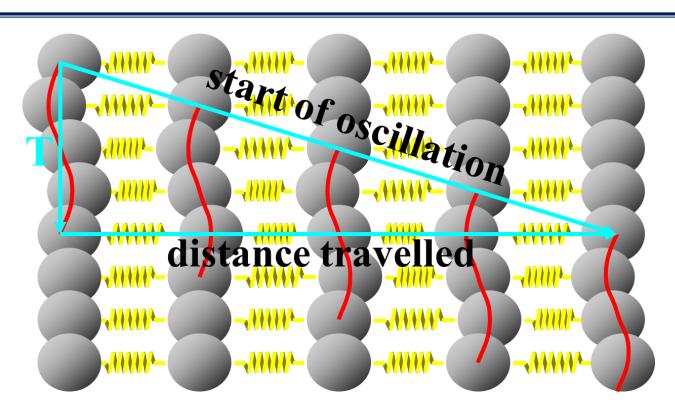




Understanding wave propagation:





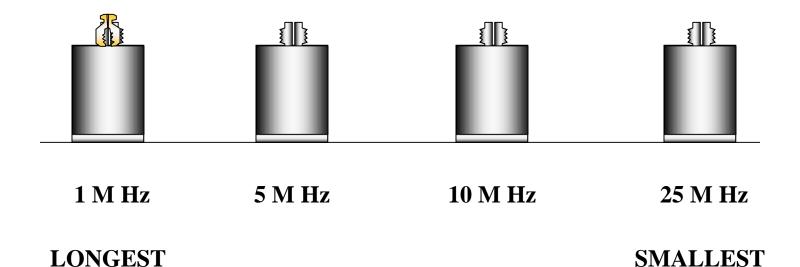


From this we derive:

Wave equation 
$$V = \frac{\lambda}{T}$$
 or  $V = \lambda f$ 







5MHz compression wave probe in steel

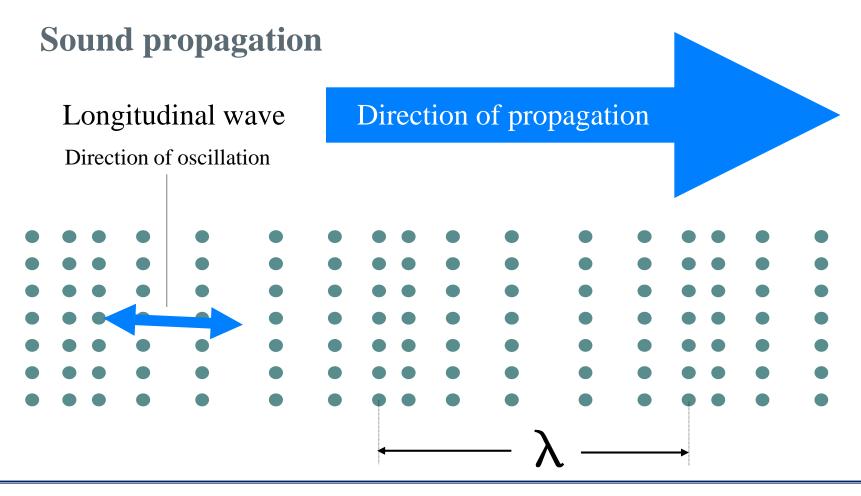
$$\lambda = \frac{V}{f} = \frac{5,900,000}{5,000,000} = 1.18mm$$



- > Several wave modes of vibration, the most common are:
  - ✓ Longitudinal or Compression wave
  - ✓ Transverse or Shear wave
  - ✓ Surface or Rayleigh wave
  - ✓ Lamb wave



#### > Longitudinal wave



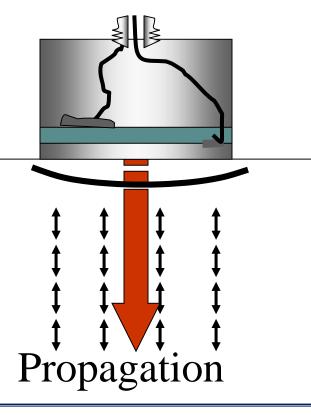


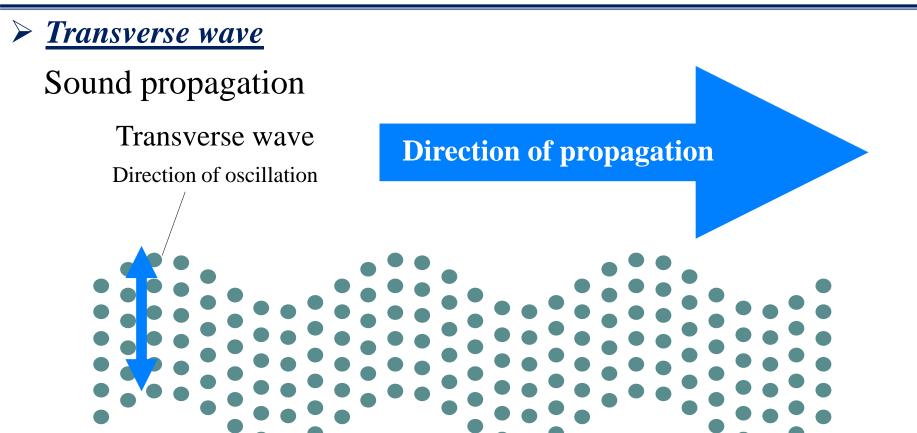
#### > Longitudinal wave

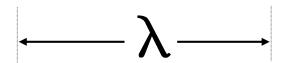
• Vibration and propagation in the same direction / parallel

• Travel in solids, liquids and gases

Particle vibration





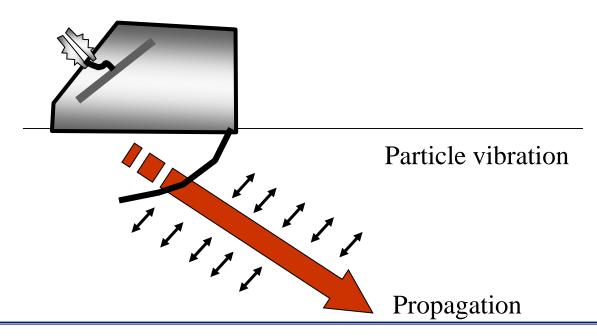






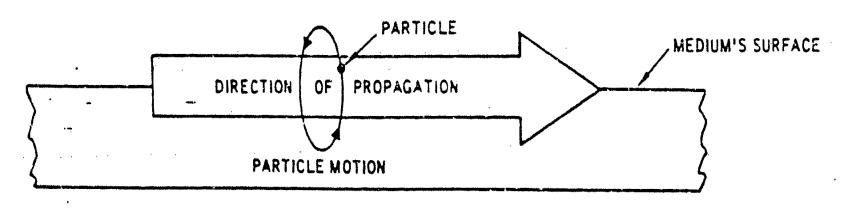
#### > Transverse wave

- Vibration at right angles / perpendicular to direction of propagation
- Travel in solids only
- Velocity  $\approx 1/2$  compression (same material)





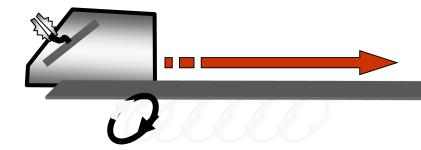
#### > Surface Wave





#### > Surface Wave

- Elliptical vibration
- Velocity 8% less than shear
- Penetrate one wavelength deep

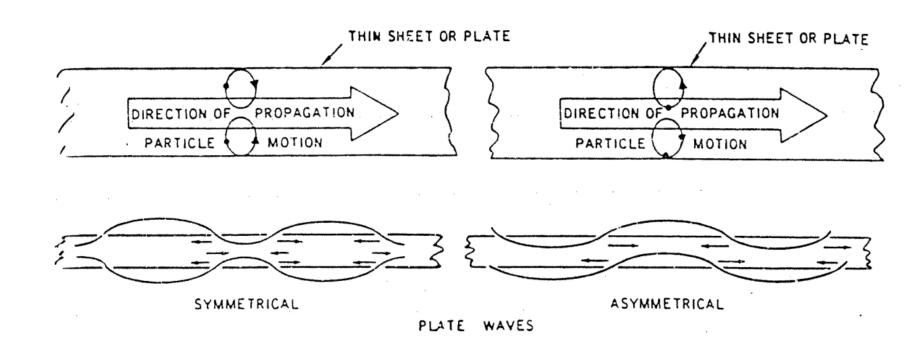


Easily dampened by heavy grease or wet finger

Follows curves but reflected by sharp corners or surface cracks

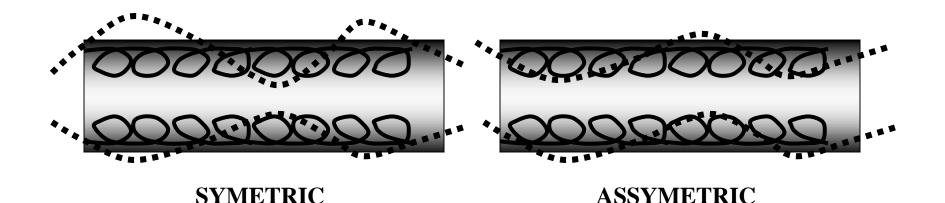


#### > Lamb Wave



#### > Lamb Wave

- Produced by the manipulation of surface waves and others
- Used mainly to test very thin materials / plates
- Velocity varies with plate thickness and frequencies







#### > Velocity

- ➤ Longitudinal waves propagate in all kind of materials.
- > Transverse waves only propagate in solid bodies.
- ➤ Due to the different type of oscillation, transverse waves travel at lower speeds.
- Sound velocity mainly depends on the density and E-modulus of the material.
- The velocity will NOT change if frequency changes, Only the wavelength changes





#### > Velocity

Velocity varies according to the material

Compression waves

Shear waves

• Steel

5960m/sec

• Steel

3245m/sec

• Water

1470m/sec

Water

NA

• Air

344m/sec

• Air

NA

Copper

4700m/sec

Copper

2330m/sec





#### > Reflection & Refraction

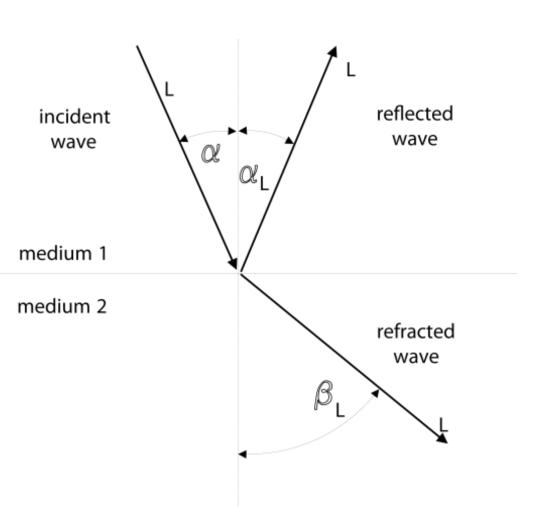
$$\sin \alpha = \sin \alpha_L$$

As a wave travels from one medium to another, its speed changes at the boundary.

The frequency of waves arriving and departing is the same.

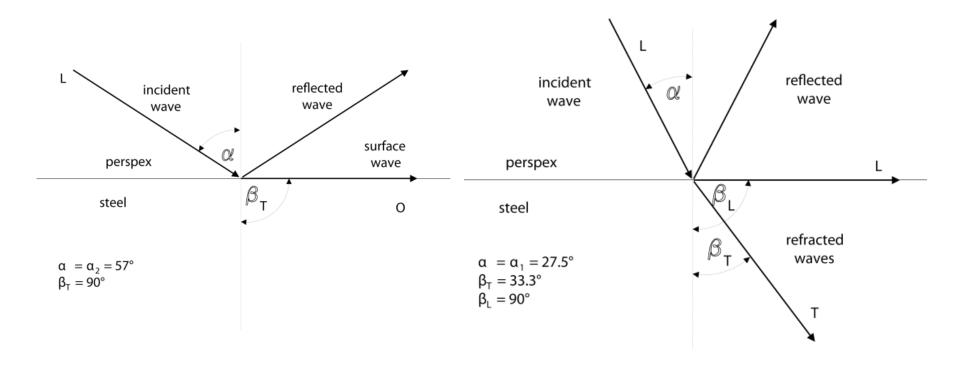
... so wavelength changes at the boundary

$$\frac{\sin\alpha}{v_1} = \frac{\sin\beta_L}{v_2} \Rightarrow \beta_L = \sin^{-1}\left(\frac{v_2.\sin\alpha}{v_1}\right)$$



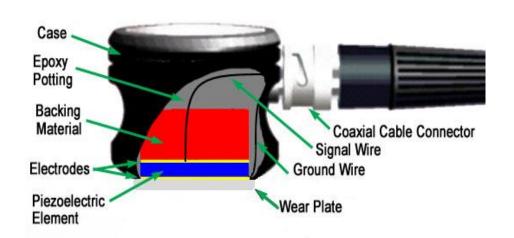


#### > Reflection & Refraction



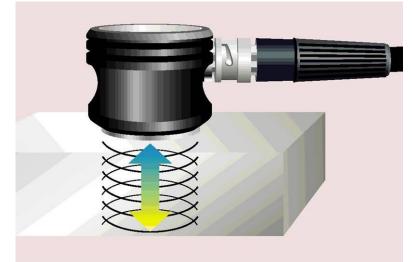
### **Ultrasound Generation**

Ultrasound is generated with a transducer.



The transducer is capable of both transmitting and receiving sound energy.

A piezoelectric element in the transducer converts electrical energy into mechanical vibrations (sound), and vice versa.





### **Test Techniques**

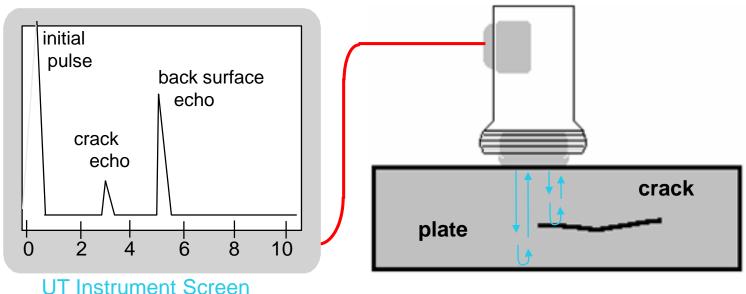
- Ultrasonic testing is a very versatile inspection method, and inspections can be accomplished in a number of different ways.
- Ultrasonic inspection techniques are commonly divided into three primary classifications.
  - Pulse-echo and Through Transmission (Relates to whether reflected or transmitted energy is used)
  - Normal Beam and Angle Beam (Relates to the angle that the sound energy enters the test article)
  - Contact and Immersion (Relates to the method of coupling the transducer to the test article)





### > Pulse-Echo

- In pulse-echo testing, a transducer sends out a pulse of energy and the same or a second transducer listens for reflected energy (an echo).
- Reflections occur due to the presence of discontinuities and the surfaces of the test article.



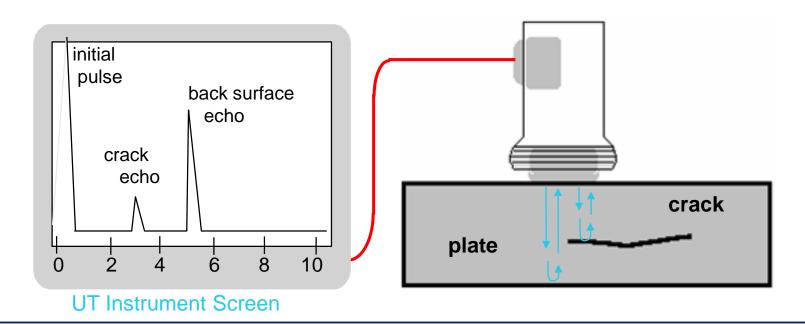






### > Pulse-Echo

• The amount of reflected sound energy is displayed versus time, which provides the inspector information about the size and the location of features that reflect the sound.

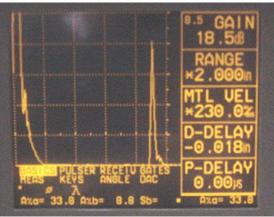






### > Pulse-Echo

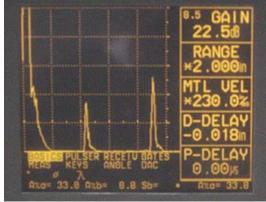




Digital display showing signal generated from sound reflecting off back surface.

Digital display showing the presence of a reflector midway through material, with lower amplitude back surface reflector.







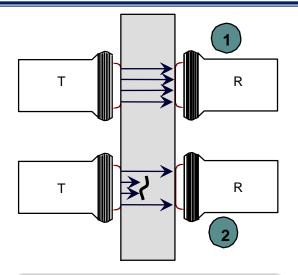
### > Pulse-Echo

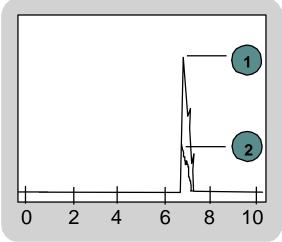
The pulse-echo technique allows testing when access to only one side of the material is possible, and it allows the location of reflectors to be precisely determined.



### > Through-Transmission

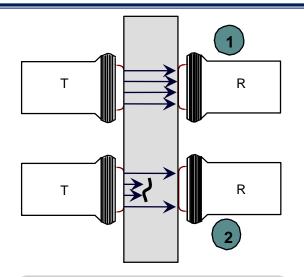
- Two transducers located on opposing sides of the test specimen are used. One transducer acts as a transmitter, the other as a receiver.
- Discontinuities in the sound path will result in a partial or total loss of sound being transmitted and be indicated by a decrease in the received signal amplitude.

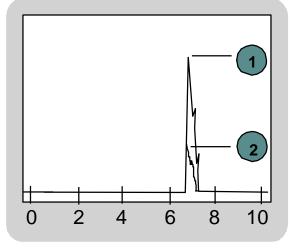




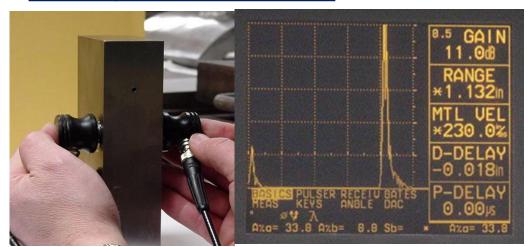
### > Through-Transmission

• Through transmission is useful in detecting discontinuities that are not good reflectors, and when signal strength is weak. It does not provide depth information.

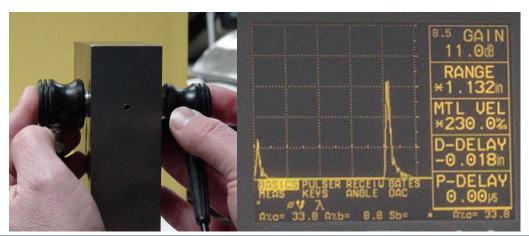




### > Through-Transmission



Digital display showing received sound through material thickness.



Digital display showing loss of received signal due to presence of a discontinuity in the sound field.

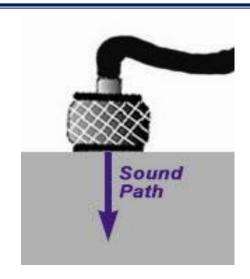


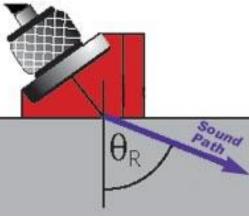
### > Normal and Angle Beam

- In normal beam testing, the sound beam is introduced into the test article at 90 degree to the surface.
- In angle beam testing, the sound beam is introduced into the test article at some angle other than 90.



- The orientation of the feature of interest the sound should be directed to produce the largest reflection from the feature.
- Obstructions on the surface of the part that must be worked around.

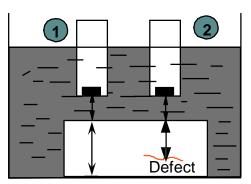


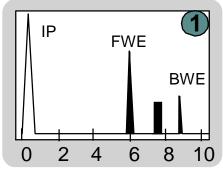


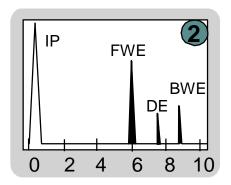


#### Contact Vs Immersion

- To get useful levels of sound energy into a material, the air between the transducer and the test article must be removed. This is referred to as coupling.
- In contact testing (shown on the previous slides) a couplant such as water, oil or a gel is applied between the transducer and the part.



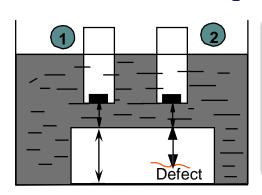


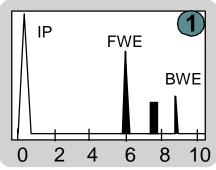


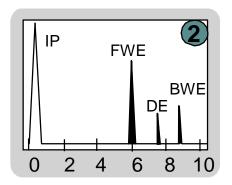
= Initial Pulse FWE = Front Wall Echo = Defect Echo BWE = Back Wall Echo

### • Contact Vs Immersion

- In immersion testing, the part and the transducer are place in a water bath. This arrangement allows better movement of the transducer while maintaining consistent coupling.
- With immersion testing, an echo from the front surface of the part is seen in the signal but otherwise signal interpretation is the same for the two techniques.







IP = Initial Pulse
FWE = Front Wall
Echo

DE = Defect Echo
BWE = Back Wall
Echo



Some of the applications for which ultrasonic testing may be employed include:

- Flaw detection (cracks, inclusions, porosity, etc.)
- Erosion & corrosion and thickness gauging
- Assessment of bond integrity in adhesively joined and brazed components
- Estimation of void content in composites and plastics
- Measurement of case hardening depth in steels
- Estimation of grain size in metals





### Thickness Gauging

• Ultrasonic thickness gauging is routinely utilized in the petrochemical and utility industries to determine various degrees of corrosion/erosion.



 Applications include piping systems, storage and containment facilities, and pressure vessels.





#### • Flaw Detection - Delaminations

Contact, pulse-echo inspection for delaminations on 36" rolled beam.





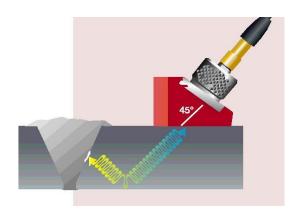
Signal showing multiple back surface echoes in an unflawed area.

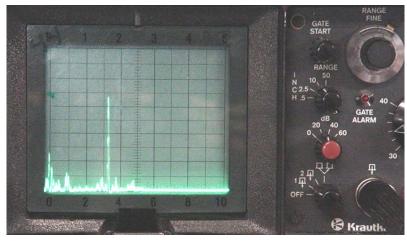


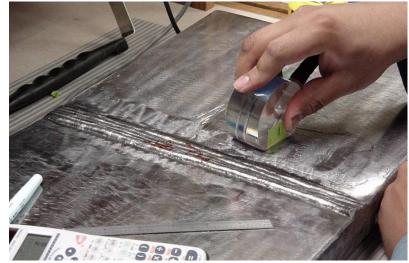
Additional echoes indicate delaminations in the member.

### • Flaw Detection in Welds

- One of the most widely used methods of inspecting weldments is ultrasonic inspection.
- Full penetration groove welds lend themselves readily to angle beam shear wave examination.









Equipment for ultrasonic testing is very diversified. Proper selection is important to insure accurate inspection data as desired for specific applications.

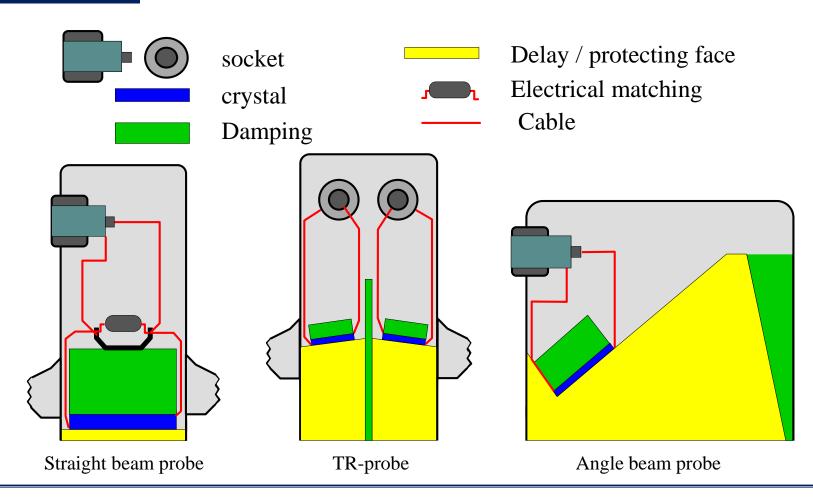
In general, there are three basic components that comprise an ultrasonic test system:

- Instrumentation
- Transducers
- Calibration Standards

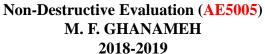




### • <u>Transducers</u>









### Transducers

- Transducers are manufactured in a variety of forms, shapes and sizes for varying applications.
- Transducers are categorized in a number of ways which include:
  - Contact or immersion
  - Single or dual element
  - Normal or angle beam
- In selecting a transducer for a given application, it is important to choose the desired frequency, bandwidth, size, and in some cases focusing which optimizes the inspection capabilities.

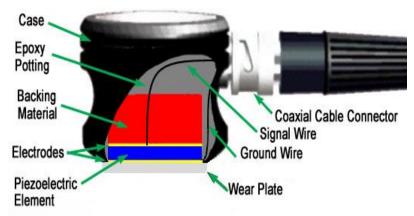


#### Contact Transducers

Contact transducers are designed to withstand rigorous use, and usually have a wear plate on the bottom surface to protect the piezoelectric element from contact with the surface of the test article.

Many incorporate ergonomic designs for ease of grip while scanning along the surface.

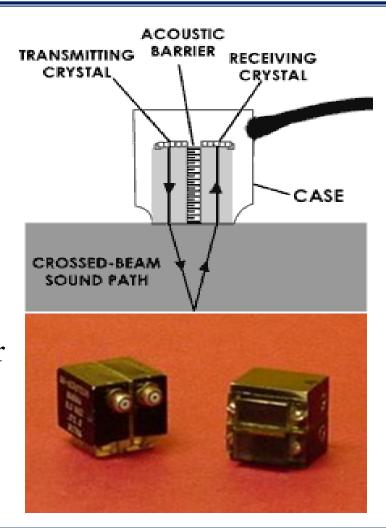






### • Contact Transducers

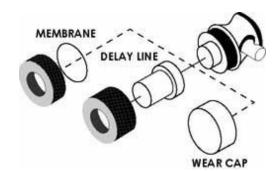
- Contact transducers are available with two piezoelectric crystals in one housing. These transducers are called dual element transducers.
- One crystal acts as a transmitter, the other as a receiver.
- This arrangement improves near surface resolution because the second transducer does not need to complete a transmit function before listening for echoes.
- Dual elements are commonly employed in thickness gauging of thin materials.





### Contact Transducers

- A way to improve near surface resolution with a single element transducer is through the use of a delay line.
- Delay line transducers have a plastic piece that is a sound path that provides a time delay between the sound generation and reception of reflected energy.





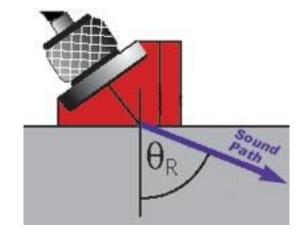
- Interchangeable pieces make it possible to configure the transducer with insulating wear caps or flexible membranes that conform to rough surfaces.
- Common applications include thickness gauging and high temperature measurements.





#### Contact Transducers

- Angle beam transducers incorporate wedges to introduce a refracted shear wave into a material.
- The incident wedge angle is used with the material velocity to determine the desired refracted shear wave according to Snell's Law)
- Transducers can use fixed or variable wedge angles.
- Common application is in weld examination.

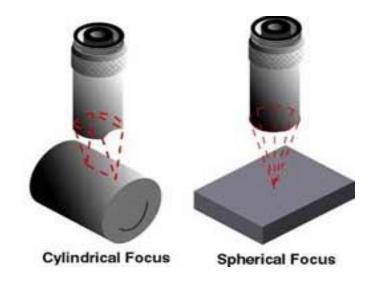






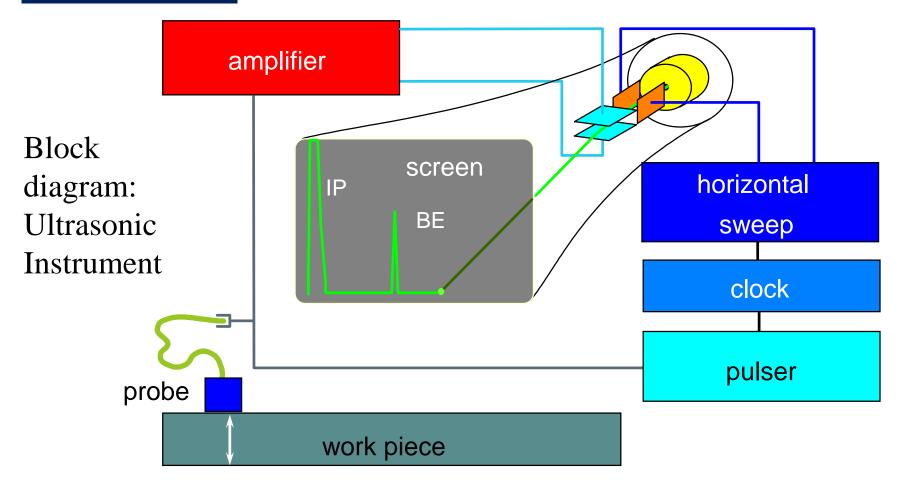
### Contact Transducers

- Immersion transducers are designed to transmit sound whereby the transducer and test specimen are immersed in a liquid coupling medium (usually water).
- Immersion transducers are manufactured with planar, cylindrical or spherical acoustic lenses (focusing lens).











- Ultrasonic equipment is usually purchased to satisfy specific inspection needs, some users may purchase general purpose equipment to fulfill a number of inspection applications.
- Test equipment can be classified in a number of different ways, this may include portable or stationary, contact or immersion, manual or automated.
- Further classification of instruments commonly divides them into four general categories: D-meters, Flaw detectors, Industrial and special application.



#### Instrumentation

- D-meters or digital thickness gauge instruments provide the user with a digital (numeric) readout.
- They are designed primarily for corrosion/erosion inspection applications.





• Some instruments provide the user with both a digital readout and a display of the signal. A distinct advantage of these units is that they allow the user to evaluate the signal to ensure that the digital measurements are of the desired features.



- Flaw detectors are instruments designed primarily for the inspection of components for defects.
- However, the signal can be evaluated to obtain other information such as material thickness values.
- Both analog and digital display.
- Offer the user options of gating horizontal sweep and amplitude threshold.







- Industrial flaw detection instruments, provide users with more options than standard flaw detectors.
- May be modulated units allowing users to tailor the instrument for their specific needs.
- Generally not as portable as standard flaw detectors.

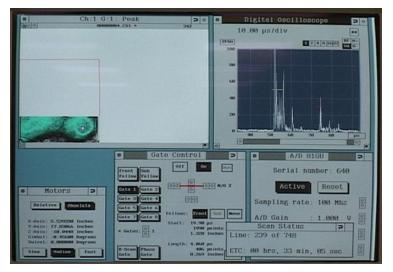






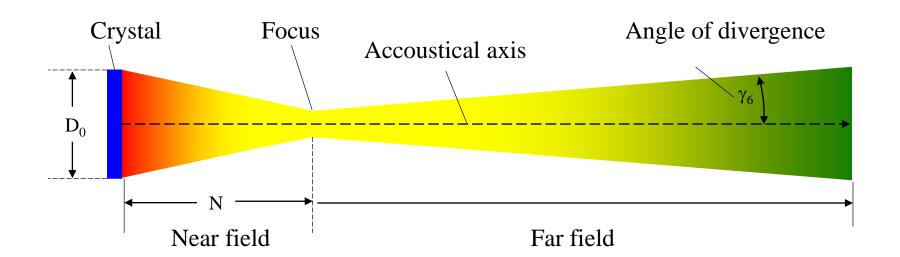
- •Immersion ultrasonic scanning systems are used for automated data acquisition and imaging.
- •They integrate an immersion tank, ultrasonic instrumentation, a scanning bridge, and computer controls.
- •The signal strength and/or the time-of-flight of the signal is measured for every point in the scan plan.
- •The value of the data is plotted using colors or shades of gray to produce detailed images of the surface or internal features of a component.



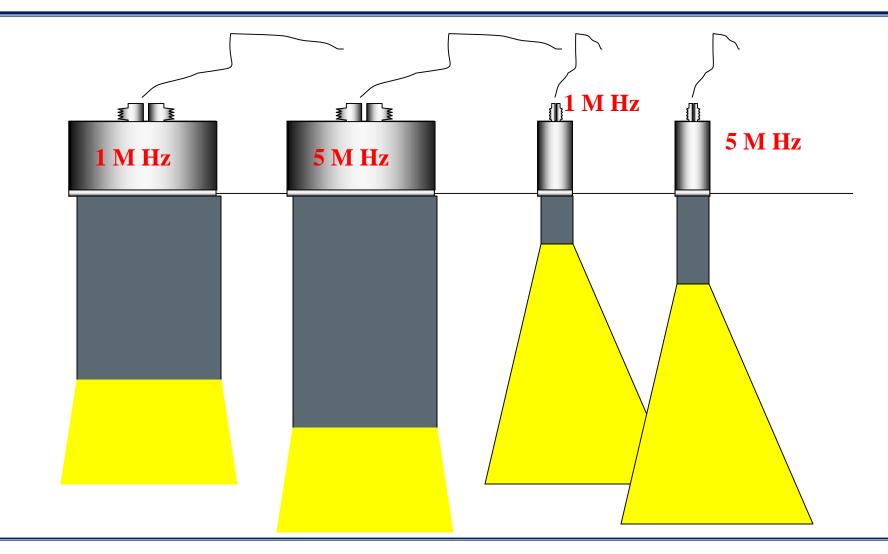




## Sound field



## Sound field





### **Calibration Standards**

Calibration is a operation of configuring the ultrasonic test equipment to known values. This provides the inspector with a means of comparing test signals to known measurements.

Calibration standards come in a wide variety of material types, and configurations due to the diversity of inspection applications.

Calibration standards are typically manufactured from materials of the same acoustic properties as those of the test articles.

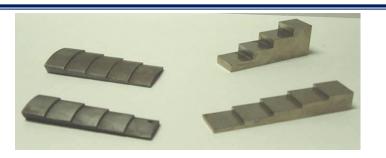
The following slides provide examples of specific types of standards.

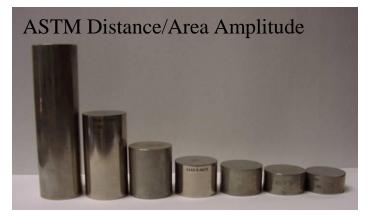


### **Calibration Standards**

Thickness calibration standards may be flat or curved for pipe and tubing applications, consisting of simple variations in material thickness.

Distance/Area Amplitude standards utilize flat bottom holes or side drilled holes to establish known reflector size with changes in sound path form the entry surface.







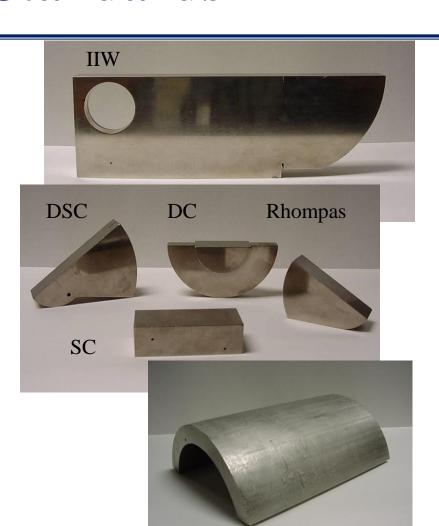




### **Calibration Standards**

There are also calibration standards for use in angle beam inspections when flaws are not parallel to entry surface.

These standards utilized side drilled holes, notches, and geometric configuration to establish time distance and amplitude relationships.

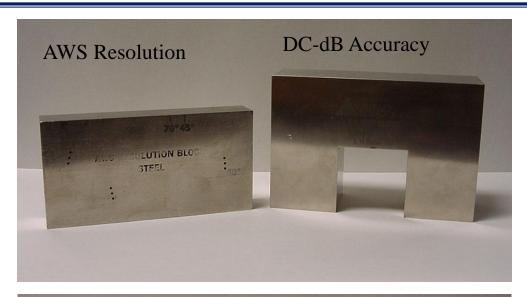




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## **Qualification Standards**

Qualification standards differ from calibration standards in that their use is for purposes of varying proper equipment operation and qualification of equipment use for specific codes and standards.







- Information from ultrasonic testing can be presented in a number of differing formats.
- Three of the more common formats include:
  - A-scan
  - B-scan
  - C-scan

These three formats will be discussed in the next few slides.

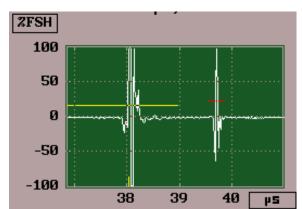




### • A-scan

- A-scan presentation displays the amount of received ultrasonic energy as a function of time.
- Relative discontinuity size can be estimated by comparing the signal amplitude to that from a known reflector.
- Reflector depth can be determined by the position of the signal on the horizontal sweep.

Signal Amplitude



Signal Amplitude

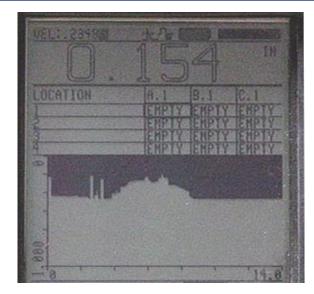






### • <u>B-scan</u>

- B-scan presentations display a profile view (cross-sectional) of a test specimen.
- Only the reflector depth in the cross-section and the linear dimensions can be determined.
- A limitation to this display technique is that reflectors may be masked by larger reflectors near the surface.







### C-scan

- The C-scan presentation displays a plan type view of the test specimen and discontinuities.
- C-scan presentations are produced with an automated data acquisition system, such as in immersion scanning.

• Use of A-scan in conjunction with C-scan is necessary when depth

determination is desired.

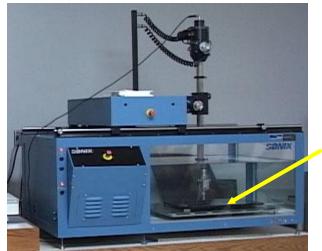
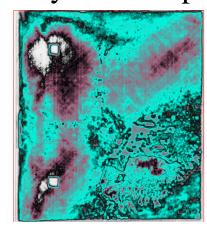


Photo of a Composite Component



C-Scan Image of Internal Features

#### Instrumentation

Images Produced With an Ultrasonic Immersion Scanning System

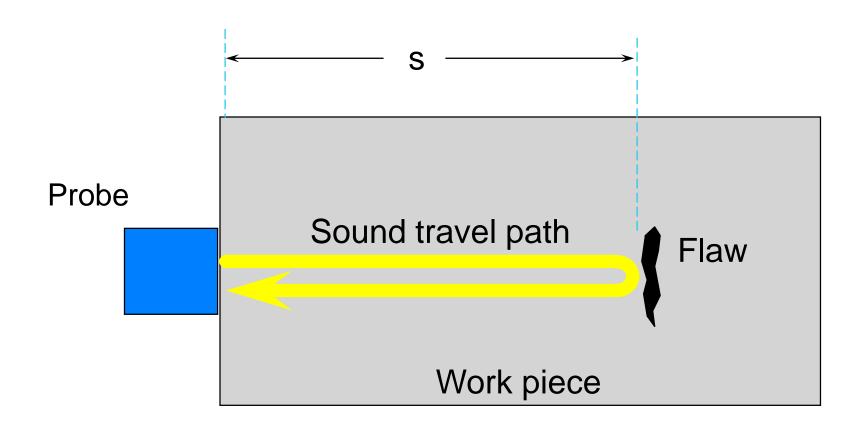


Gray scale image produced using the sound reflected from the front surface of the coin



Gray scale image produced using the sound reflected from the back surface of the coin (inspected from "heads" side)

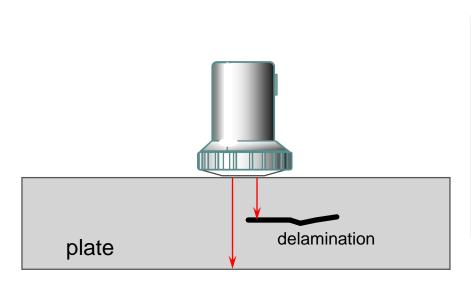
# **Indications Analysis**

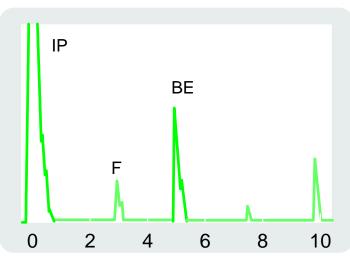




# **Indications Analysis**

### Plate testing





IP = Initial pulse

F = Flaw

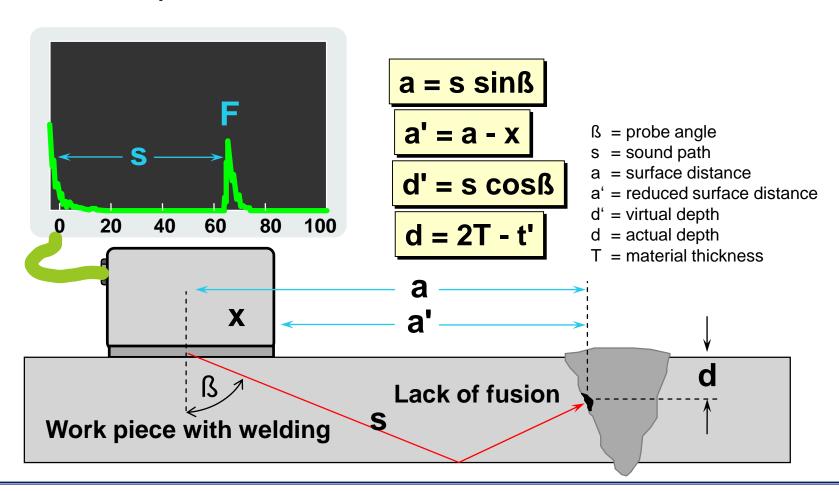
BE = Backwall echo

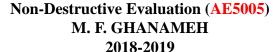




# **Indications Analysis**

### Weld inspection







- Acoustical properties: ultrasonic material characteristics such as velocity, impedance, and attenuation.
- **ASTM:** acronym for American Society for Testing and Materials. This society is extensively involved in establishing standards for materials and the testing of materials.
- **Back reflection:** a display signal that corresponds to the far surface of a test specimen, side opposite to transducer when testing with longitudinal waves.
- **Band width:** a range of frequencies either transmitted or received, may be narrow or broad range.
- **B-scan:** presentation technique displaying data in a cross-sectional view.





- Calibration: a sequence of instrument control adjustments/instrument responses using known values to verify instrument operating characteristics. Allows determination of unknown quantities from test materials.
- **CRT:** acronym for Cathode Ray Tube. Vacuum tube that utilizes one or more electron guns for generating an image.
- C-scan: presentation technique that displays specimen data in a plan type view.
- DAC (Distance Amplitude Correction-curves): a graphical method of allowing for material attenuation. Percentage of DAC is often used as a means of acceptance criteria.
- **Discontinuity:** an interruption in the physical structure of a material, examples include fissures, cracks, and porosity.





- IIW: calibration standard meeting the specification of the International Institute of Welding.
- Longitudinal (Compression) waves: ultrasonic mode of propagation in which the particle vibration is parallel to the direction of propagation.
- Near Surface Resolution: the ability of an ultrasonic system to display reflectors located close to the entry surface.
- Pulse-echo: ultrasonic test method that utilizes reflected sound as a means of collecting test data.
- Rayleigh (Surface) waves: ultrasonic mode of propagation where the sound travels along the surface, particle vibration is elliptical.





- **Reflection:** the changing in direction of sound waves as they strike a surface.
- Snell's Law: an equation of ratios used to determine incident or refracted angle of sound, denotes angle/velocity relationship.
- Sweep display: horizontal line on the lower portion of the display, often called the time base line.
- Through transmission: test technique in which ultrasound is transmitted from one transducer and received by a separate transducer on the opposite side of the test specimen.
- Wavelength: the distance that a sound wave travels as it completes one cycle, normally measured in inches or millimeters.

